

> restart

> Sistema := diff(Vc(t), t) = -10·Vc(t) - 10·II(t) + 120·cos(120·Pi·t), diff(II(t), t) =  $\frac{1}{10}$ ·Vc(t) -  $\frac{3}{10}$ ·II(t) : Sistema[1]; Sistema[2]

$$\frac{d}{dt} Vc(t) = -10 Vc(t) - 10 II(t) + 120 \cos(120 \pi t)$$

$$\frac{d}{dt} II(t) = \frac{1}{10} Vc(t) - \frac{3}{10} II(t) \quad (1)$$

> AA := array([[-10, -10], [ $\frac{1}{10}$ ,  $-\frac{3}{10}$ ]])

$$AA := \begin{bmatrix} -10 & -10 \\ \frac{1}{10} & -\frac{3}{10} \end{bmatrix} \quad (2)$$

> Xcero := array([0, 0])

$$Xcero := \begin{bmatrix} 0 & 0 \end{bmatrix} \quad (3)$$

> BB := array([120·cos(120·Pi·t), 0])

$$BB := \begin{bmatrix} 120 \cos(120 \pi t) & 0 \end{bmatrix} \quad (4)$$

> with(linalg) :

> MatExp := exponential(AA, t) : evalf(%, 2)

$$\begin{bmatrix} 1.0 e^{-10. t} - 0.01 e^{-0.20 t} & 1.1 e^{-10. t} - 1.1 e^{-0.20 t} \\ -0.011 e^{-10. t} + 0.011 e^{-0.20 t} & -0.01 e^{-10. t} + 1.0 e^{-0.20 t} \end{bmatrix} \quad (5)$$

> SolHom := evalm(MatExp &\* Xcero)

$$SolHom := \begin{bmatrix} 0 & 0 \end{bmatrix} \quad (6)$$

> MatExpTau := map(rcurry(eval, t = t - tau), MatExp) : evalf(%, 2)

$$\begin{bmatrix} 1.0 e^{-10. t + 10. \tau} - 0.01 e^{-0.20 t + 0.20 \tau} & 1.1 e^{-10. t + 10. \tau} - 1.1 e^{-0.20 t + 0.20 \tau} \\ -0.011 e^{-10. t + 10. \tau} + 0.011 e^{-0.20 t + 0.20 \tau} & -0.01 e^{-10. t + 10. \tau} + 1.0 e^{-0.20 t + 0.20 \tau} \end{bmatrix} \quad (7)$$

> BBtau := map(rcurry(eval, t = tau), BB)

$$BBtau := \begin{bmatrix} 120 \cos(120 \pi \tau) & 0 \end{bmatrix} \quad (8)$$

> ProdTau := evalm(MatExpTau &\* BBtau) : evalf(%, 2)

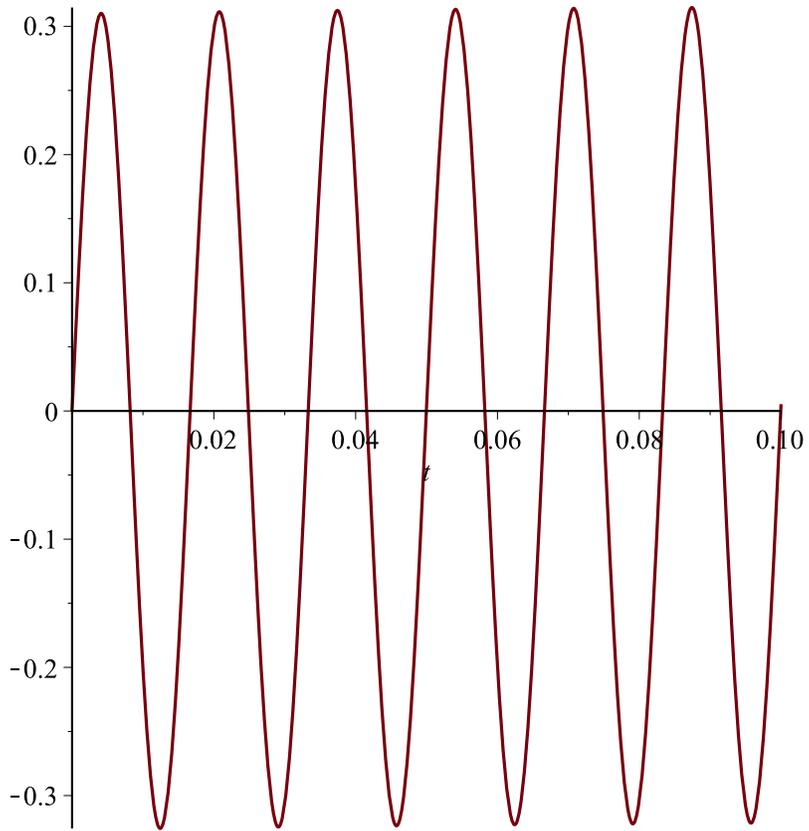
$$\begin{bmatrix} 120. (1.0 e^{-10. t + 10. \tau} - 0.01 e^{-0.20 t + 0.20 \tau}) \cos(370. \tau), 120. (-0.011 e^{-10. t + 10. \tau} + 0.011 e^{-0.20 t + 0.20 \tau}) \cos(370. \tau) \end{bmatrix} \quad (9)$$

> SolNoHom := map(int, ProdTau, tau = 0 .. t) : Vc(t) = evalf(SolNoHom[1], 2); II(t) = evalf(SolNoHom[2], 2)

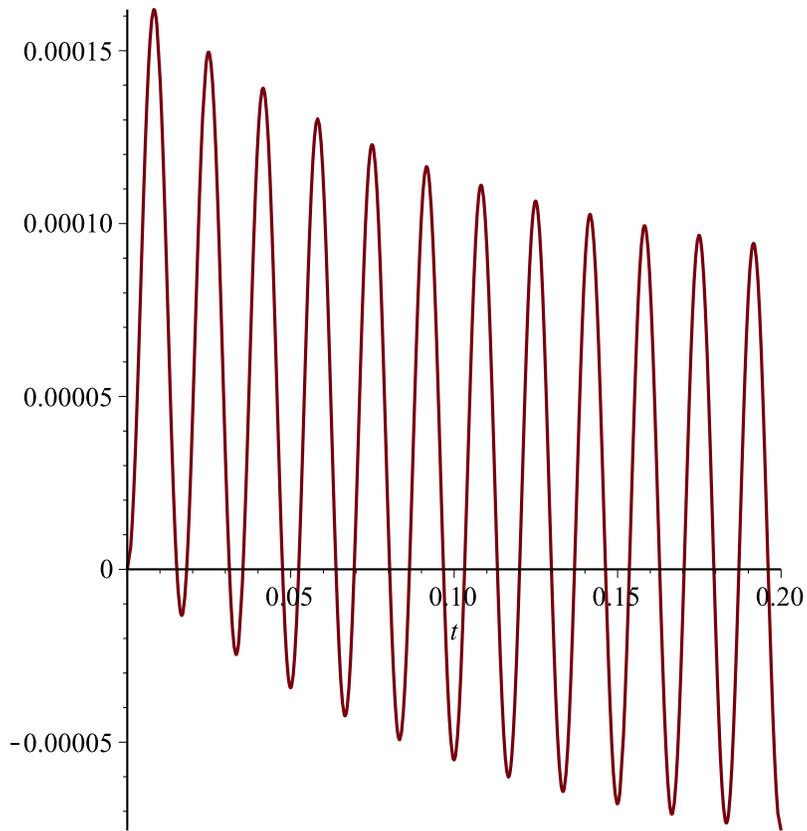
$$Vc(t) = -0.0090 e^{-10. t} + 0.32 \sin(370. t) + 0.0085 \cos(370. t)$$

$$II(t) = 0.000090 e^{-10. t} - 0.000085 \cos(370. t) + 0.000024 \sin(370. t) \quad (10)$$

> plot(SolNoHom[1], t = 0 .. 0.1)



```
> plot(SolNoHom[2], t=0..0.2)
```



> restart

> Sist := diff(x[1](t), t) = v[1](t), diff(x[2](t), t) = v[2](t), diff(v[1](t), t)  
 =  $\frac{(-k[1] - k[2])}{M[1]} \cdot x[1](t) + \frac{k[2]}{M[1]} \cdot x[2](t)$ , diff(v[2](t), t) =  $\frac{k[2]}{M[2]} \cdot x[1](t)$   
 -  $\frac{k[2]}{M[2]} \cdot x[2](t)$  : Sist[1]; Sist[2]; Sist[3]; Sist[4]

$$\frac{d}{dt} x_1(t) = v_1(t)$$

$$\frac{d}{dt} x_2(t) = v_2(t)$$

$$\frac{d}{dt} v_1(t) = \frac{(-k_1 - k_2) x_1(t)}{M_1} + \frac{k_2 x_2(t)}{M_1}$$

$$\frac{d}{dt} v_2(t) = \frac{k_2 x_1(t)}{M_2} - \frac{k_2 x_2(t)}{M_2}$$

(11)

> Xcero := array([ [  $\frac{1}{10}$ ,  $\frac{1}{10}$ , 0, 0 ] ])

(12)

$$X_{cero} := \begin{bmatrix} \frac{1}{10} & \frac{1}{10} & 0 & 0 \end{bmatrix} \quad (12)$$

```
> k[1] := 4; k[2] := 2; M[1] := 1; M[2] := 1;
      k1 := 4
      k2 := 2
      M1 := 1
      M2 := 1
```

```
> with(linalg) :
```

```
> AA := array([[0, 0, 1, 0], [0, 0, 0, 1], [
      (-k[1] - k[2]) / M[1], k[2] / M[1], 0, 0], [
      k[2] / M[2], -k[2] / M[2], 0,
      0]])
```

$$AA := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -6 & 2 & 0 & 0 \\ 2 & -2 & 0 & 0 \end{bmatrix} \quad (14)$$

```
> MatExp := exponential(AA, t) : evalf(MatExp[1, 1], 2)
      0.15 cos(1.1 t) + 0.88 cos(2.6 t) + 0.017 I sin(1.1 t)
```

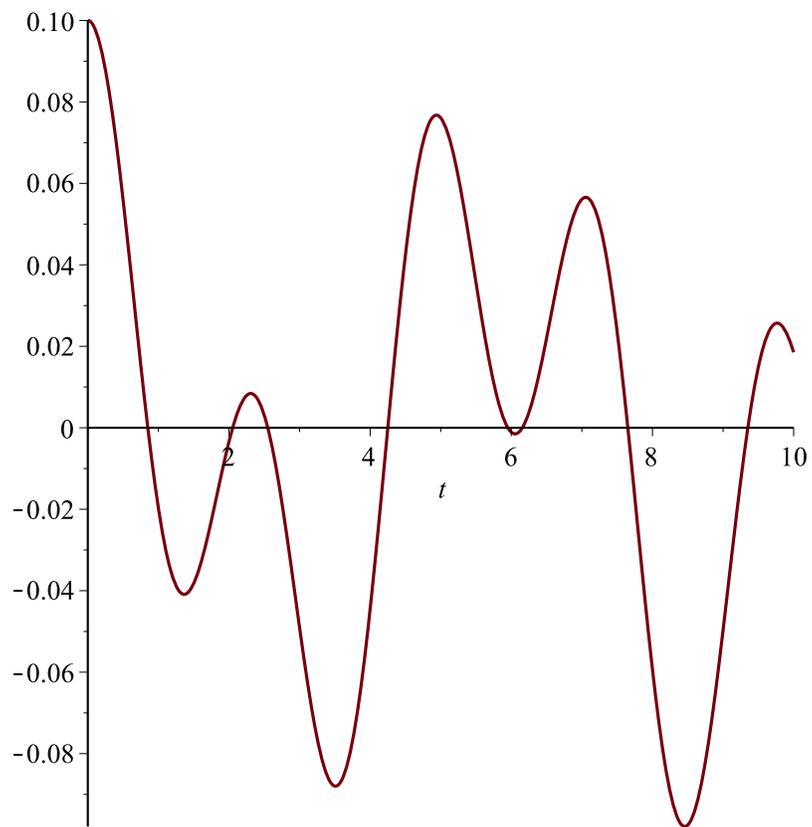
```
> SolPart := evalm(MatExp &* Xcero) : x[1](t) = evalf(SolPart[1], 2); x[2](t)
      = evalf(SolPart[2], 2)
```

$$x_1(t) = 0.051 \cos(1.1 t) + 0.052 \cos(2.6 t) + 0.0017 I \sin(1.1 t)$$

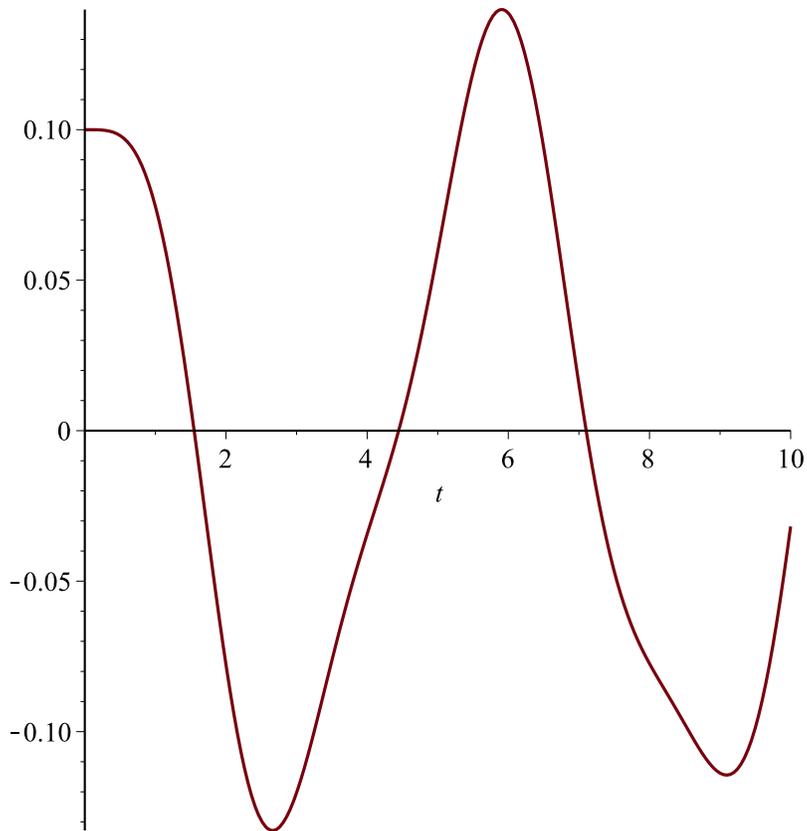
$$x_2(t) = 0.13 \cos(1.1 t) - 0.022 \cos(2.6 t) + 0.0017 I \sin(1.1 t)$$

```
> plot(SolPart[1], t=0..10)
```

(16)



```
> plot(SolPart[2], t = 0 .. 10)
```



> restart

> Sist := diff(x[1](t), t) = v[1](t), diff(x[2](t), t) = v[2](t), diff(v[1](t), t)  
 =  $\frac{(-k[1] - k[2])}{M[1]} \cdot x[1](t) + \frac{k[2]}{M[1]} \cdot x[2](t)$ , diff(v[2](t), t) =  $\frac{k[2]}{M[2]} \cdot x[1](t)$   
 -  $\frac{k[2]}{M[2]} \cdot x[2](t)$  : Sist[1]; Sist[2]; Sist[3]; Sist[4]

$$\frac{d}{dt} x_1(t) = v_1(t)$$

$$\frac{d}{dt} x_2(t) = v_2(t)$$

$$\frac{d}{dt} v_1(t) = \frac{(-k_1 - k_2) x_1(t)}{M_1} + \frac{k_2 x_2(t)}{M_1}$$

$$\frac{d}{dt} v_2(t) = \frac{k_2 x_1(t)}{M_2} - \frac{k_2 x_2(t)}{M_2}$$

(17)

> Xcero := array([ [  $\frac{1}{10}$ ,  $\frac{1}{10}$ , 0, 0 ] ])

(18)

$$X_{cero} := \begin{bmatrix} \frac{1}{10} & \frac{1}{10} & 0 & 0 \end{bmatrix} \quad (18)$$

```
> k[1] := 2; k[2] := 4; M[1] := 1; M[2] := 1;
      k1 := 2
      k2 := 4
      M1 := 1
      M2 := 1
```

```
> with(linalg) :
```

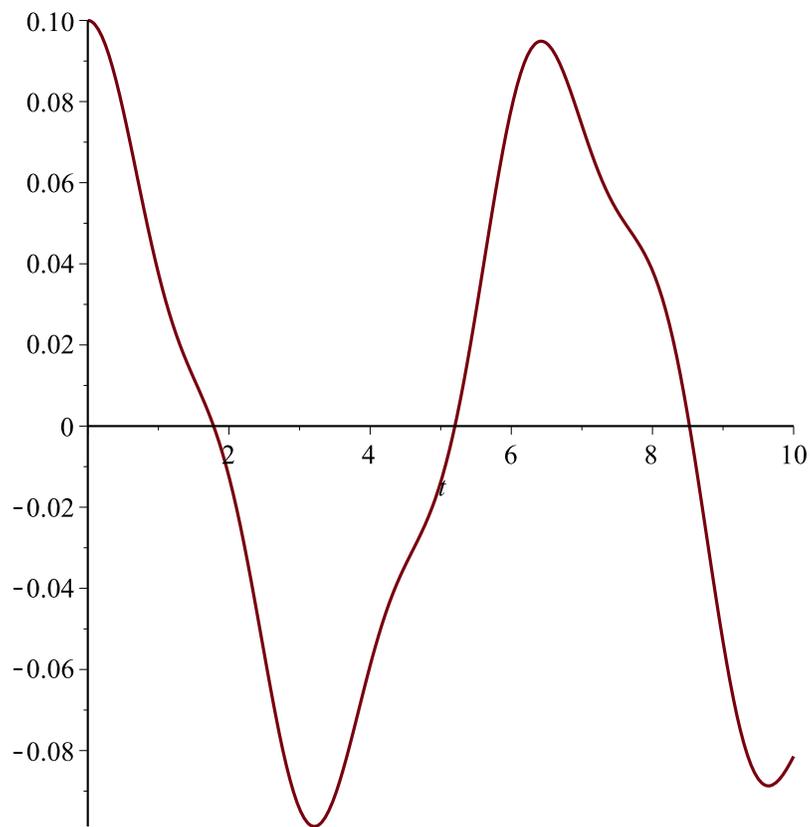
```
> AA := array([[0, 0, 1, 0], [0, 0, 0, 1], [
      (-k[1] - k[2]) / M[1], k[2] / M[1], 0, 0], [
      k[2] / M[2], -k[2] / M[2], 0,
      0]])
```

$$AA := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -6 & 4 & 0 & 0 \\ 4 & -4 & 0 & 0 \end{bmatrix} \quad (20)$$

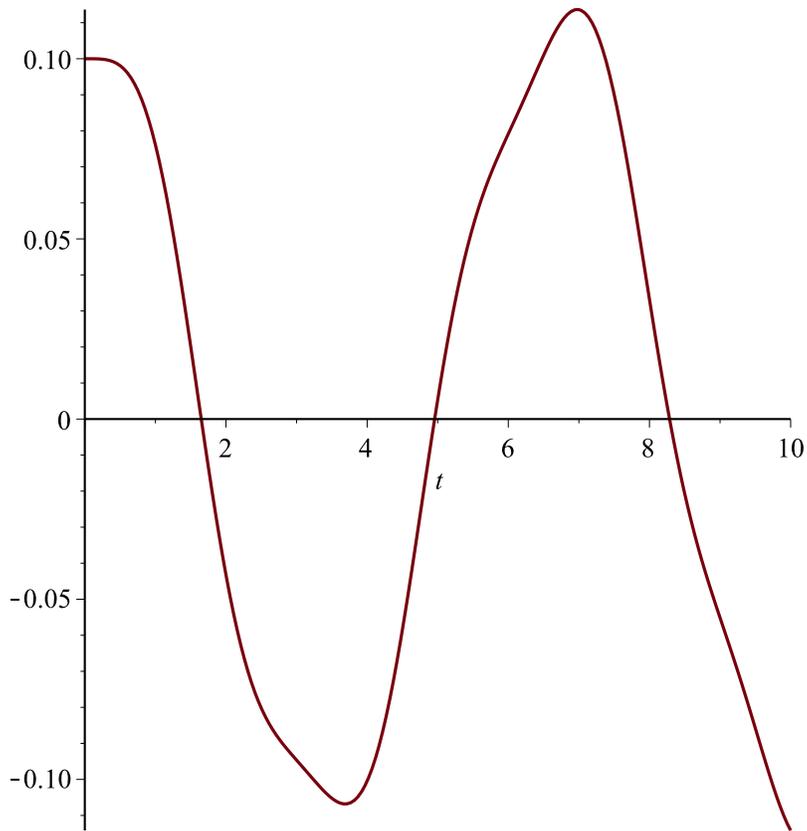
```
> MatExp := exponential(AA, t) : evalf(MatExp[1, 1], 2)
      0.41 cos(0.95 t) + 0.61 cos(3.0 t) \quad (21)
```

```
> SolPart := evalm(MatExp &* Xcero) : x[1](t) = evalf(SolPart[1], 2); x[2](t)
      = evalf(SolPart[2], 2)
      x1(t) = 0.089 cos(0.95 t) + 0.013 cos(3.0 t)
      x2(t) = 0.11 cos(0.95 t) - 0.011 cos(3.0 t) \quad (22)
```

```
> plot(SolPart[1], t=0..10)
```



```
=  
> plot(SolPart[2], t=0..10)
```



> restart

> Sist := diff(x[1](t), t) = v[1](t), diff(x[2](t), t) = v[2](t), diff(v[1](t), t)  
 =  $\frac{(-k[1] - k[2])}{M[1]} \cdot x[1](t) + \frac{k[2]}{M[1]} \cdot x[2](t)$ , diff(v[2](t), t) =  $\frac{k[2]}{M[2]} \cdot x[1](t)$   
 -  $\frac{k[2]}{M[2]} \cdot x[2](t)$  : Sist[1]; Sist[2]; Sist[3]; Sist[4]

$$\frac{d}{dt} x_1(t) = v_1(t)$$

$$\frac{d}{dt} x_2(t) = v_2(t)$$

$$\frac{d}{dt} v_1(t) = \frac{(-k_1 - k_2) x_1(t)}{M_1} + \frac{k_2 x_2(t)}{M_1}$$

$$\frac{d}{dt} v_2(t) = \frac{k_2 x_1(t)}{M_2} - \frac{k_2 x_2(t)}{M_2}$$

(23)

> Xcero := array([ [  $\frac{1}{10}$ ,  $\frac{1}{10}$ , 0, 0 ] ])

(24)

$$X_{cero} := \begin{bmatrix} \frac{1}{10} & \frac{1}{10} & 0 & 0 \end{bmatrix} \quad (24)$$

```
> k[1] := 4; k[2] := 2; M[1] := 1; M[2] := 2;
      k1 := 4
      k2 := 2
      M1 := 1
      M2 := 2
```

```
> with(linalg) :
```

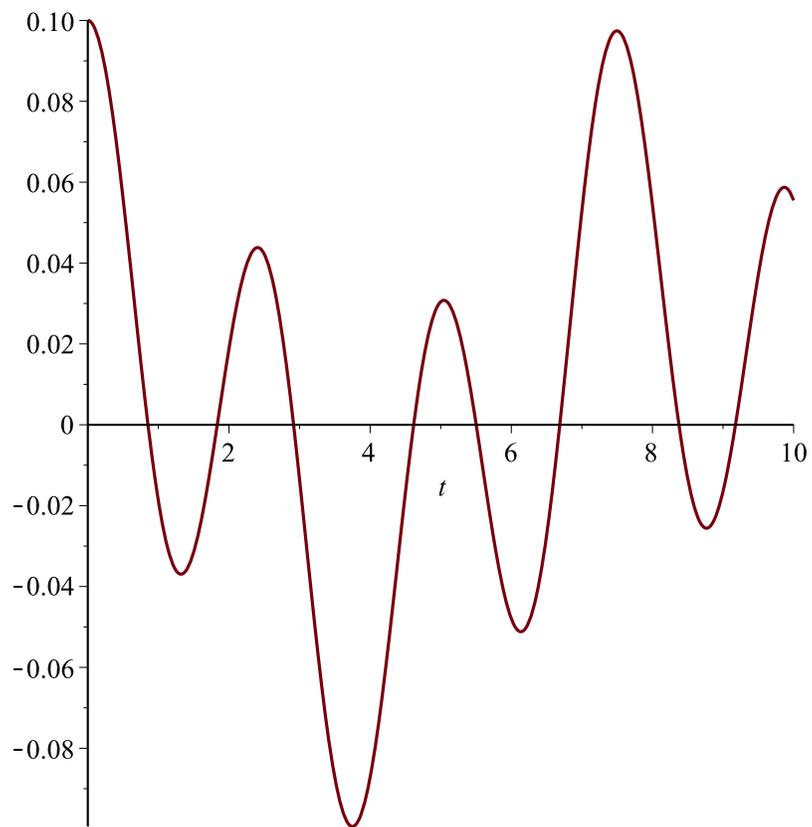
```
> AA := array([[0, 0, 1, 0], [0, 0, 0, 1], [
      (-k[1] - k[2]) / M[1], k[2] / M[1], 0, 0], [
      k[2] / M[2], -k[2] / M[2], 0,
      0]])
```

$$AA := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -6 & 2 & 0 & 0 \\ 1 & -1 & 0 & 0 \end{bmatrix} \quad (26)$$

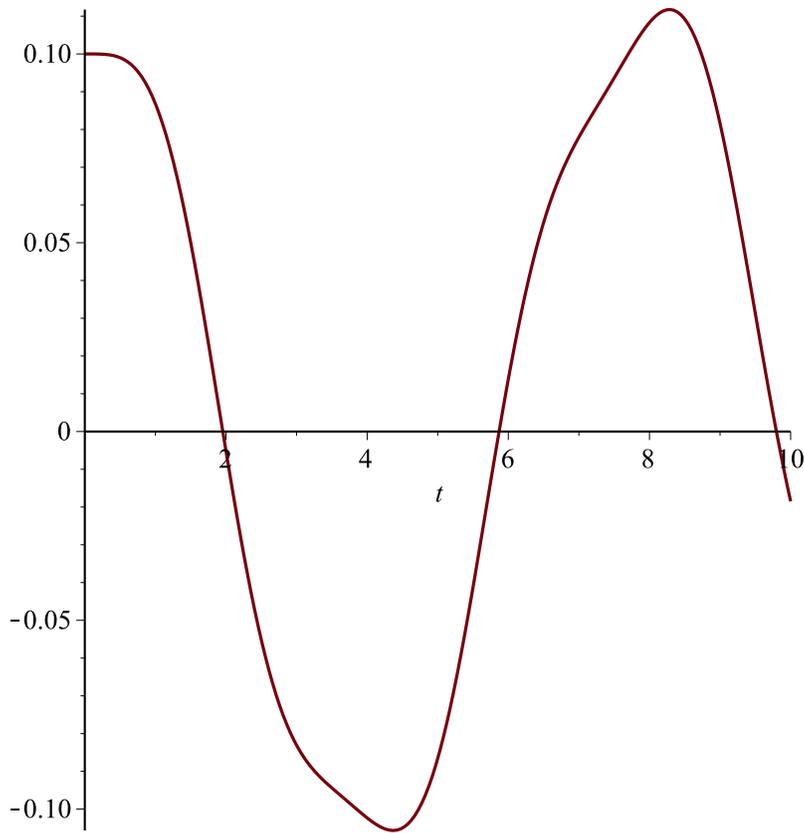
```
> MatExp := exponential(AA, t) : evalf(MatExp[1, 1], 2)
      0.072 cos(-0.75 t) + 0.89 cos(2.4 t)
```

```
> SolPart := evalm(MatExp &* Xcero) : x[1](t) = evalf(SolPart[1], 2); x[2](t)
      = evalf(SolPart[2], 2)
      x1(t) = 0.041 cos(-0.75 t) + 0.055 cos(2.4 t)
      x2(t) = 0.11 cos(-0.75 t) - 0.0098 cos(2.4 t)
```

```
> plot(SolPart[1], t=0..10)
```



```
> plot(SolPart[2], t = 0 .. 10)
```



> restart

> Sist := diff(x[1](t), t) = v[1](t), diff(x[2](t), t) = v[2](t), diff(v[1](t), t)  
 =  $\frac{-k[1] - k[2]}{M[1]} \cdot x[1](t) + \frac{k[2]}{M[1]} \cdot x[2](t)$ , diff(v[2](t), t) =  $\frac{k[2]}{M[2]} \cdot x[1](t)$   
 -  $\frac{k[2]}{M[2]} \cdot x[2](t)$  : Sist[1]; Sist[2]; Sist[3]; Sist[4]

$$\frac{d}{dt} x_1(t) = v_1(t)$$

$$\frac{d}{dt} x_2(t) = v_2(t)$$

$$\frac{d}{dt} v_1(t) = \frac{(-k_1 - k_2) x_1(t)}{M_1} + \frac{k_2 x_2(t)}{M_1}$$

$$\frac{d}{dt} v_2(t) = \frac{k_2 x_1(t)}{M_2} - \frac{k_2 x_2(t)}{M_2}$$

(29)

> Xcero := array([[1/10, 1/10, 0, 0]])

(30)

$$X_{cero} := \begin{bmatrix} \frac{1}{10} & \frac{1}{10} & 0 & 0 \end{bmatrix} \quad (30)$$

```
> k[1] := 4; k[2] := 2; M[1] := 2; M[2] := 1;
      k1 := 4
      k2 := 2
      M1 := 2
      M2 := 1
```

```
> with(linalg) :
```

```
> AA := array([[0, 0, 1, 0], [0, 0, 0, 1], [
      (-k[1] - k[2]) / M[1], k[2] / M[1], 0, 0], [
      k[2] / M[2], -k[2] / M[2], 0,
      0]])
```

$$AA := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -3 & 1 & 0 & 0 \\ 2 & -2 & 0 & 0 \end{bmatrix} \quad (32)$$

```
> MatExp := exponential(AA, t) : evalf(MatExp[1, 1], 2)
      0.33 cos(t) + 0.67 cos(2. t)
```

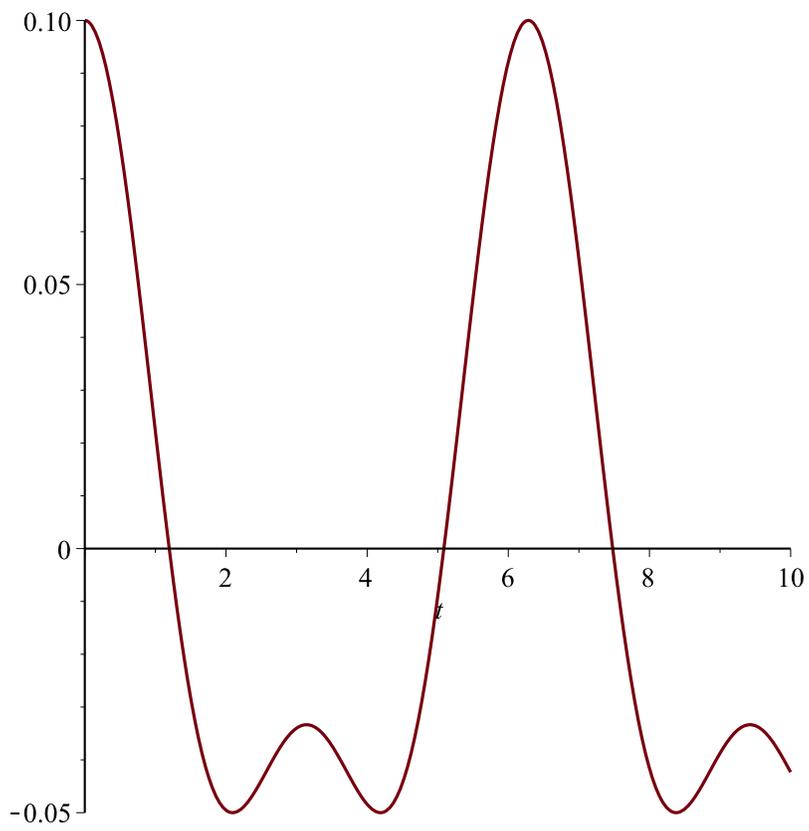
```
> SolPart := evalm(MatExp &* Xcero) : x[1](t) = evalf(SolPart[1], 2); x[2](t)
      = evalf(SolPart[2], 2)
```

$$x_1(t) = 0.067 \cos(t) + 0.033 \cos(2. t)$$

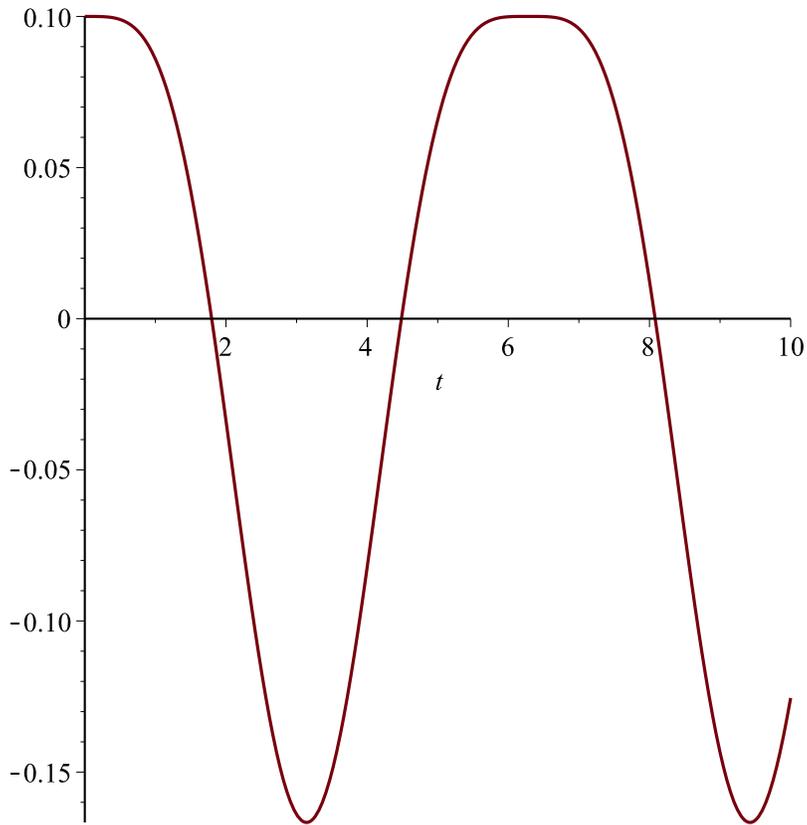
$$x_2(t) = 0.13 \cos(t) - 0.033 \cos(2. t)$$

```
> plot(SolPart[1], t=0..10)
```

(34)



```
> plot(SolPart[2], t = 0..10)
```



> restart

> Sist := diff(x[1](t), t) = v[1](t), diff(x[2](t), t) = v[2](t), diff(v[1](t), t)  
 =  $\frac{(-k[1] - k[2])}{M[1]} \cdot x[1](t) + \frac{k[2]}{M[1]} \cdot x[2](t)$ , diff(v[2](t), t) =  $\frac{k[2]}{M[2]} \cdot x[1](t)$   
 -  $\frac{k[2]}{M[2]} \cdot x[2](t)$  : Sist[1]; Sist[2]; Sist[3]; Sist[4]

$$\frac{d}{dt} x_1(t) = v_1(t)$$

$$\frac{d}{dt} x_2(t) = v_2(t)$$

$$\frac{d}{dt} v_1(t) = \frac{(-k_1 - k_2) x_1(t)}{M_1} + \frac{k_2 x_2(t)}{M_1}$$

$$\frac{d}{dt} v_2(t) = \frac{k_2 x_1(t)}{M_2} - \frac{k_2 x_2(t)}{M_2}$$

(35)

> Xcero := array([ [  $\frac{1}{10}$ ,  $\frac{1}{10}$ , 0, 0 ] ])

(36)

$$X_{cero} := \begin{bmatrix} \frac{1}{10} & \frac{1}{10} & 0 & 0 \end{bmatrix} \quad (36)$$

```
> k[1] := 4; k[2] := 2; M[1] := 1; M[2] := 1;
      k1 := 4
      k2 := 2
      M1 := 1
      M2 := 1
```

```
> with(linalg) :
```

```
> AA := array([[0, 0, 1, 0], [0, 0, 0, 1], [
      (-k[1] - k[2]) / M[1], k[2] / M[1], 0, 0], [
      k[2] / M[2], -k[2] / M[2], 0,
      0]])
```

$$AA := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -6 & 2 & 0 & 0 \\ 2 & -2 & 0 & 0 \end{bmatrix} \quad (38)$$

```
> MatExp := exponential(AA, t) : evalf(MatExp[1, 1], 2)
      0.15 cos(1.1 t) + 0.88 cos(2.6 t) + 0.017 I sin(1.1 t)
```

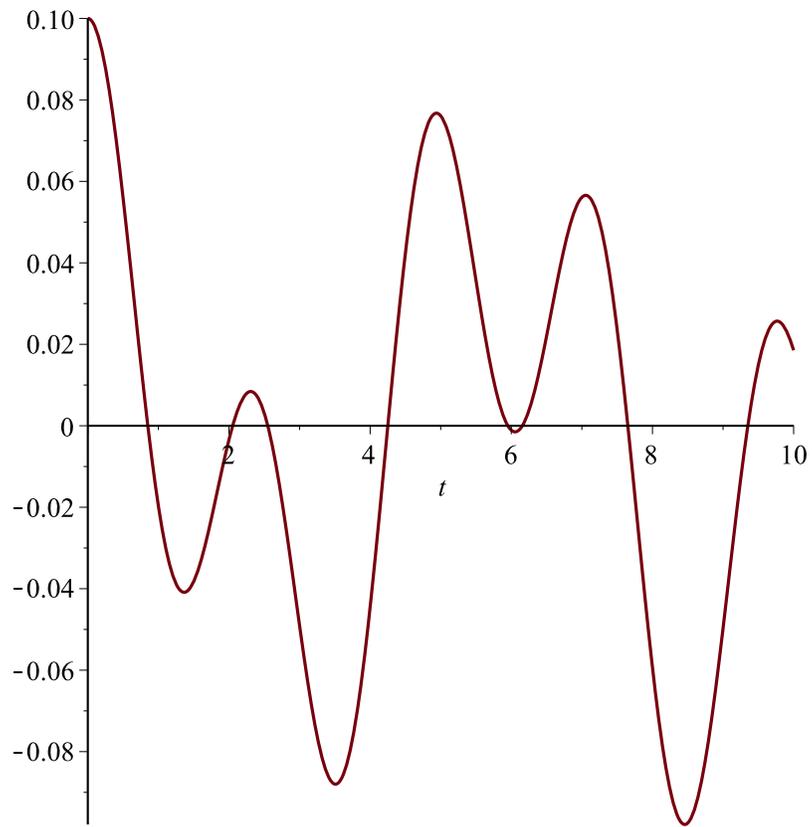
```
> SolPart := evalm(MatExp &* Xcero) : x[1](t) = evalf(SolPart[1], 2); x[2](t)
      = evalf(SolPart[2], 2)
```

$$x_1(t) = 0.051 \cos(1.1 t) + 0.052 \cos(2.6 t) + 0.0017 I \sin(1.1 t)$$

$$x_2(t) = 0.13 \cos(1.1 t) - 0.022 \cos(2.6 t) + 0.0017 I \sin(1.1 t)$$

```
> plot(SolPart[1], t=0..10)
```

(40)



```
> plot(SolPart[2], t = 0 .. 10)
```

