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> restart
> SistEcuadif := diff(x[1](t), t) = 2·x[1](t) + 3·x[2](t), diff(x[2](t), t) = x[1](t) + 4
·x[2](t) : SistEcuadif[1]; SistEcuadif[2]

$$\begin{aligned}\frac{d}{dt} x_1(t) &= 2 x_1(t) + 3 x_2(t) \\ \frac{d}{dt} x_2(t) &= x_1(t) + 4 x_2(t)\end{aligned}\tag{1}$$

> AA := array([ [2, 3], [1, 4] ])

$$AA := \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}\tag{2}$$

> with(linalg) :
> MatExp := exponential(AA, t)

$$MatExp := \begin{bmatrix} \frac{3}{4} e^t + \frac{1}{4} e^{5t} & \frac{3}{4} e^{5t} - \frac{3}{4} e^t \\ \frac{1}{4} e^{5t} - \frac{1}{4} e^t & \frac{1}{4} e^t + \frac{3}{4} e^{5t} \end{bmatrix}\tag{3}$$

> Fcero := array([_C1, _C2])

$$Fcero := \begin{bmatrix} \_C1 & \_C2 \end{bmatrix}\tag{4}$$

> SolGral := evalm(MatExp &* Fcero) : x[1](t) = SolGral[1]; x[2](t) = SolGral[2];

$$\begin{aligned}x_1(t) &= \left( \frac{3}{4} e^t + \frac{1}{4} e^{5t} \right) \_C1 + \left( \frac{3}{4} e^{5t} - \frac{3}{4} e^t \right) \_C2 \\ x_2(t) &= \left( \frac{1}{4} e^{5t} - \frac{1}{4} e^t \right) \_C1 + \left( \frac{1}{4} e^t + \frac{3}{4} e^{5t} \right) \_C2\end{aligned}\tag{5}$$

> SistEcuadif[1]

$$\frac{d}{dt} x_1(t) = 2 x_1(t) + 3 x_2(t)\tag{6}$$

> SistEcuadif[2]

$$\frac{d}{dt} x_2(t) = x_1(t) + 4 x_2(t)\tag{7}$$

>
> ComprobarUno := simplify(eval(subs(x[1](t) = SolGral[1], x[2](t) = SolGral[2],
lhs(SistEcuadif[1]) - rhs(SistEcuadif[1]) = 0)))
ComprobarUno := 0 = 0\tag{8}
> ComprobarDos := simplify(eval(subs(x[1](t) = SolGral[1], x[2](t) = SolGral[2],
lhs(SistEcuadif[2]) - rhs(SistEcuadif[2]) = 0)))
ComprobarDos := 0 = 0\tag{9}
>

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