





$$M_1 \frac{d^2 x_1(t)}{dt^2} = -H_1 x_1(t) + H_2 (x_2(t) - x_1(t))$$

$$M_2 \frac{d^2 x_2(t)}{dt^2} = -H_2 (x_2(t) - x_1(t))$$

S(4) EDO(1) Lcch.

$$\left. \begin{array}{l} x_1(0) = a_1 \\ x_2(0) = a_2 \\ x_3(0) = 0 \\ x_4(0) = 0 \end{array} \right\} \text{C.I.}$$

$$\left\{ \begin{array}{l} \frac{dx_1(t)}{dt} = x_3(t) \\ \frac{dx_2(t)}{dt} = x_4(t) \\ \frac{dx_3(t)}{dt} = \left( -\frac{H_1}{M_1} - \frac{H_2}{M_1} \right) x_1(t) + \frac{H_2}{M_1} (x_2(t)) \\ \frac{dx_4(t)}{dt} = \frac{H_2}{M_2} x_1(t) - \frac{H_2}{M_2} x_2(t) \end{array} \right.$$

$$\frac{d}{dt} \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ x_4(t) \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -\left(\frac{H_1}{M_1} + \frac{H_2}{M_1}\right) & \frac{H_2}{M_1} & 0 & 0 \\ \frac{H_2}{M_2} & -\frac{H_2}{M_2} & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ x_4(t) \end{bmatrix}$$

