

$$e^{At} \longrightarrow A$$

$$\frac{d}{dt} e^{At} = A e^{At}$$

$$\left[\frac{d}{dt} e^{At} \right]_{t=0} = A \left[e^{At} \right]_{t=0}$$

$$\left[\frac{d}{dt} e^{At} \right]_{t=0} = A \cdot \underline{I}$$

$$MatExp := \begin{bmatrix} e^t \cos(t) & e^t \sin(t) \\ -e^t \sin(t) & e^t \cos(t) \end{bmatrix}$$

$$MatExp = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} e^t \cos(t) + \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} e^t \sin(t)$$

$$AA = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \quad \leftarrow$$

$$\begin{cases} \frac{dx(t)}{dt} = x(t) + y(t) \\ \frac{dy(t)}{dt} = -x(t) + y(t) \end{cases}$$

$$x(0) = 8$$

$$y(0) = -8$$

$$\boxed{\begin{aligned}\frac{dx_1(t)}{dt} &= x_2(t) \\ \frac{dx_2(t)}{dt} &= -x_1(t)\end{aligned}} \quad \frac{d}{dt} \bar{x}(t) = \underset{AA.}{\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

$$\frac{d^2 x_1(t)}{dt^2} = \frac{dx_2(t)}{dt}$$

$$\frac{d^2 x_1(t)}{dt^2} = -x_1(t)$$

$$\frac{d^2 \bar{x}_1(t)}{dt^2} + x_1(t) = 0 \quad \text{EDO(2) LCC}$$

$$m^2 + 1 = 0 \quad m_1 = i \quad m_2 = -i.$$

$$\begin{cases} x_1(t) = c_1 \cos(t) + c_2 \sin(t) \end{cases}$$

$$\begin{cases} x_2(t) = -c_1 \sin(t) + c_2 \cos(t) \end{cases}$$

$$\bar{x}(t) = \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \quad A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$\frac{d}{dt} e^{At} = \begin{bmatrix} -\sin(t) & \cos(t) \\ -\cos(t) & -\sin(t) \end{bmatrix}$$

$$\left. \frac{d}{dt} e^{At} \right|_{t=0} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$\frac{d^2 x_1(t)}{dt^2} + a_1 \frac{dx_1(t)}{dt} + a_2 x_1(t) = 0$$

$\pm \text{DO}(2) \hookrightarrow \text{CCH.}$

$$\left[\begin{array}{l} m^2 + a_1 m + a_2 = 0 \quad \left. \begin{array}{l} m_1 = a + bi \\ m_2 = a - bi \end{array} \right\} m_1, m_2 \in \mathbb{C} \\ y_g = C_1 e^{at} \cos(bt) + C_2 e^{at} \sin(bt) \end{array} \right.$$

$$m^2 + a_2 = 0 \quad m_1 = \sqrt{a_2} i \quad m_2 = -\sqrt{a_2} i$$

$$y_g = C_1 \cos(\sqrt{a_2} t) + C_2 \sin(\sqrt{a_2} t)$$

$$\begin{array}{|l} x + y = 4 \\ 2x + 2y = 5 \end{array}$$

$$\frac{dx(t)}{dt} = x(t) + y(t)$$

$$\frac{dy(t)}{dt} = 2x(t) + 2y(t)$$

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

$$x(0) = 2 \quad y(0) = -2$$

$$\begin{aligned}
 x(t) &= C_1 + C_2 e^{3t} \\
 y(t) &= 2 C_2 e^{3t} - C_1
 \end{aligned}
 \Leftrightarrow
 \begin{aligned}
 x(t) &= \left(\frac{2}{3} + \frac{1}{3} e^{3t} \right) x_0 + \left(\frac{1}{3} e^{3t} - \frac{1}{3} \right) y_0 \\
 y(t) &= \left(\frac{2}{3} e^{3t} - \frac{2}{3} \right) x_0 + \left(\frac{1}{3} + \frac{2}{3} e^{3t} \right) y_0
 \end{aligned}$$

$$\begin{aligned}
 x(t) &= \left(\frac{2}{3} x_0 - \frac{1}{3} y_0 \right) + \left(\frac{1}{3} x_0 + \frac{1}{3} y_0 \right) e^{3t} \\
 y(t) &= \left(-\frac{2}{3} x_0 + \frac{1}{3} y_0 \right) + \left(\frac{2}{3} x_0 + \frac{2}{3} y_0 \right) e^{3t}
 \end{aligned}$$

$$C_1 = \frac{2}{3} x_0 - \frac{1}{3} y_0 \quad C_2 = \frac{1}{3} x_0 + \frac{1}{3} y_0$$

$$X(t) = C_1 + C_2 e^{3t}$$

$$Y(t) = -C_1 + 2C_2 e^{3t}$$

Jefe División DCB.

Dr. Gerardo Espinosa Pérez.

Tutor Posgrado en Control.