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> restart
> Sistema := diff(x[1](t), t) = x[1](t) + x[2](t) + 5·exp(t), diff(x[2](t), t) = -x[1](t)
+ x[2](t) - 8·t2: Sistema[1]; Sistema[2]
      
$$\frac{d}{dt} x_1(t) = x_1(t) + x_2(t) + 5 e^t$$

      
$$\frac{d}{dt} x_2(t) = -x_1(t) + x_2(t) - 8 t^2 \quad (1)$$


> CondIni := x[1](0) = 2, x[2](0) = -3
      CondIni := x1(0) = 2, x2(0) = -3 \quad (2)

> AA := array([ [1, 1], [-1, 1] ])
      AA := 
$$\begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \quad (3)$$


> Xzero := array([2, -3])
      Xzero := 
$$\begin{bmatrix} 2 & -3 \end{bmatrix} \quad (4)$$


> BB := array([ 5·exp(t), -8·t2 ])
      BB := 
$$\begin{bmatrix} 5 e^t & -8 t^2 \end{bmatrix} \quad (5)$$


> with(linalg):
> MatExp := exponential(AA, t)
      MatExp := 
$$\begin{bmatrix} e^t \cos(t) & e^t \sin(t) \\ -e^t \sin(t) & e^t \cos(t) \end{bmatrix} \quad (6)$$


> SolHom := evalm(MatExp &* Xzero) : Xhom[1] = SolHom[1]; Xhom[2] = SolHom[2];
      Xhom1 = 2 et cos(t) - 3 et sin(t)
      Xhom2 = -2 et sin(t) - 3 et cos(t) \quad (7)

> MatExpTau := map(rcurry(eval, t = t - tau'), MatExp)
      MatExpTau := 
$$\begin{bmatrix} e^{t-\tau} \cos(t-\tau) & e^{t-\tau} \sin(t-\tau) \\ -e^{t-\tau} \sin(t-\tau) & e^{t-\tau} \cos(t-\tau) \end{bmatrix} \quad (8)$$


> BBtau := map(rcurry(eval, t = tau'), BB)
      BBtau := 
$$\begin{bmatrix} 5 e^\tau & -8 \tau^2 \end{bmatrix} \quad (9)$$


> ProdTau := evalm(MatExpTau &* BBtau) : ProdTau[1]; ProdTau[2]
      5 et-\tau cos(t - τ) eτ - 8 et-\tau sin(t - τ) τ2
      - 5 et-\tau sin(t - τ) eτ - 8 et-\tau cos(t - τ) τ2 \quad (10)

> SolNoHom := simplify(map(int, ProdTau, tau = 0 .. t)) : XnoHom[1] = SolNoHom[1];
      XnoHom[2] = SolNoHom[2]
      XnoHom1 = (4 cos(t) + 9 sin(t)) et - 4 (t + 1)2
      XnoHom2 = -4 + 4 t2 + et (-5 + 9 cos(t) - 4 sin(t)) \quad (11)

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> ComprobarUno[1] := simplify(subs(t=0, SolNoHom[1]))  

      ComprobarUno1 := 0  

(12)

> ComprobarUno[2] := simplify(subs(t=0, SolNoHom[2]))  

      ComprobarUno2 := 0  

(13)

> SolPartFinal := evalm(SolHom + SolNoHom) : x[1](t) = SolPartFinal[1]; x[2](t)  

      = SolPartFinal[2]  

      x1(t) = 2 et cos(t) - 3 et sin(t) + (4 cos(t) + 9 sin(t)) et - 4 (t + 1)2  

      x2(t) = -2 et sin(t) - 3 et cos(t) - 4 + 4 t2 + et (-5 + 9 cos(t) - 4 sin(t))  

(14)

> ComprobarDos[1] := simplify(subs(t=0, SolPartFinal[1]))  

      ComprobarDos1 := 2  

(15)

> ComprobarDos[2] := simplify(subs(t=0, SolPartFinal[2]))  

      ComprobarDos2 := -3  

(16)

> Sistema[1]  

      
$$\frac{d}{dt} x_1(t) = x_1(t) + x_2(t) + 5 e^t$$
  

(17)

> ComprobarTres[1] := simplify(subs(x[1](t) = SolPartFinal[1], x[2](t) = SolPartFinal[2],  

      Sistema[1]))  

      ComprobarTres1 := 12 et cos(t) - 8 t - 8 = 12 et cos(t) - 8 t - 8  

(18)

> Sistema[2]  

      
$$\frac{d}{dt} x_2(t) = -x_1(t) + x_2(t) - 8 t^2$$
  

(19)

> ComprobarTres[2] := simplify(subs(x[1](t) = SolPartFinal[1], x[2](t) = SolPartFinal[2],  

      Sistema[2]))  

      ComprobarTres2 := (-12 sin(t) - 5) et + 8 t = (-12 sin(t) - 5) et + 8 t  

(20)

> restart
> Ecua := diff(z(x,y), x$2) + 8 · diff(z(x,y), y$2) = 0  

      Ecua :=  $\frac{\partial^2}{\partial x^2} z(x,y) + 8 \frac{\partial^2}{\partial y^2} z(x,y) = 0$   

(21)

> SolGral := pdsolve(Ecua)
      SolGral := z(x,y) = f1(y - 2 I √2 x) + f2(y + 2 I √2 x)  

(22)

> restart
> Ecua := diff(z(x,y), x$2) + 4 · diff(z(x,y), x, y) - 6 · diff(z(x,y), y$2) = 0  

      Ecua :=  $\frac{\partial^2}{\partial x^2} z(x,y) + 4 \frac{\partial^2}{\partial x \partial y} z(x,y) - 6 \frac{\partial^2}{\partial y^2} z(x,y) = 0$   

(23)

> SolGral := pdsolve(Ecua)
      SolGral := z(x,y) = f1(y - (2 + √10) x) + f2(y - (2 - √10) x)  

(24)

> with(PDEtools)
[CanonicalCoordinates, ChangeSymmetry, CharacteristicQ, CharacteristicQInvariants,  

(25)

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*ConservedCurrentTest, ConservedCurrents, ConsistencyTest, D\_Dx, DeterminingPDE, Eta\_k, Euler, FirstIntegralSolver, FromJet, FunctionFieldSolutions, InfinitesimalGenerator, Infinitesimals, IntegratingFactorTest, IntegratingFactors, InvariantEquation, InvariantSolutions, InvariantTransformation, Invariants, Laplace, Library, PDEplot, PolynomialSolutions, ReducedForm, SimilaritySolutions, SimilarityTransformation, Solve, SymmetryCommutator, SymmetryGauge, SymmetrySolutions, SymmetryTest, SymmetryTransformation, TWSolutions, ToJet, ToMissingDependentVariable, build, casesplit, charstrip, dchange, dcoeffs, declare, diff\_table, difforder, dpolyform, dsolve, mapde, separability, splitstrip, splitsys, undeclare]*

> restart  
>  $Ecua := \text{diff}(z(x, y), y\$2) - 6 \cdot \text{diff}(z(x, y), x, y) + 8 \cdot \text{diff}(z(x, y), x) = z(x, y)$   
 $Ecua := \frac{\partial^2}{\partial y^2} z(x, y) - 6 \frac{\partial^2}{\partial x \partial y} z(x, y) + 8 \frac{\partial}{\partial x} z(x, y) = z(x, y)$  (26)

>  $SolGral := \text{pdsolve}(Ecua)$   
 $SolGral := z(x, y) = f_1(-\xi_2) f_2(-\xi_1)$  where  $\left[ \begin{array}{l} \left\{ \frac{d}{d \xi_2} f_1(-\xi_2) = -c_1 f_1(-\xi_2), \frac{d}{d \xi_1} f_2(-\xi_1) \right. \right.$  (27)  

$$\left. \left. = \frac{-8 c_1 f_2(-\xi_1) + f_2(-\xi_1)}{6 c_1 - \frac{4}{3}} \right\}, \text{ and } \left\{ -\xi_1 = -\frac{x}{6}, -\xi_2 = 6y + x \right\} \right]$$

>  $\text{with(PDEtools)}$  :  
>  $SolGralDos := \text{build}(SolGral)$   
 $SolGralDos := z(x, y) = \frac{c_1 c_2 \left( e^{\frac{-c_1^2 (6y+x)}{9c_1-2}} \right)^9 e^{-\frac{x}{4(9c_1-2)}}}{\left( e^{-\frac{x-c_1}{6(9c_1-2)}} \right)^{12} \left( e^{\frac{-c_1 (6y+x)}{9c_1-2}} \right)^2}$  (28)

>